



Jelvo Brushless Type C Series (Current control type)

Model DLV45C

Thirty different torque settings can be set on a single screwdriver!

- Current controlled torque system
- Low-voltage brushless motor
- ESD (Electrostatic Discharge) protection structure
- For both hand-held / automated machines (External startup)
- Nine speed settings available
- Automatic three step speed control function
- Two types of measuring methods (Time/Motor rotation signal)
- Seven color indication LED (At the tip of the screwdriver)
- Two external I/O signal connection ports (NPN ⇔ PNP switchable, RS-232C)
- Various settings can be configured via a PC (Free setting software available on NITTO KOHKI website)
- Built-in screw counting function

















Torque and fastening setting of

Ist unit

1.2 Nm 1000 min-1 2nd unit

1.8 Nm 500 min-1 3rd unit

3.0 Nm 800 min-1 4th unit

1.8 Nm 500 min⁻¹

delvo **Brushless Type** C Series (Current control type)







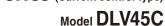


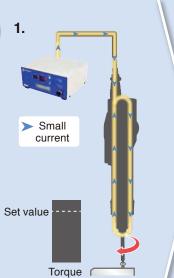


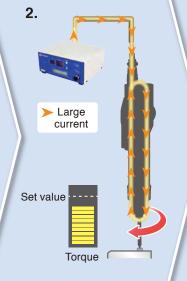


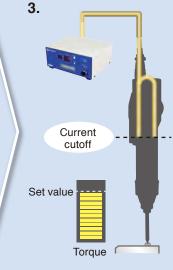












Mechanism of **Current Controlled Torque System**

COUNT

FUNCTION

1. Start of fastening

At start-up, a small amount of current is allowed.

2. During fastening

As the load increases during fastening, so does the amount of current allowed.

3. End of fastening

When the desired current value (adjusted by corresponding torque value) is reached, current flow is cut off and the screwdriver stops.

Specifications

	Model		Bit	DLV45C12L-AY K	DLV45C12P-AY K
	Starting Met	hod		Lever Start	Push to Start
	Power Source	ce		From dedica	ted controller
	Torque Adju	stment		From 1 to 100%	in 1% increments
	Torque		(Nm [lbf·in])	0.6 to 4.5 [5.3 to 39.8]
		SOFT fastening	(min ⁻¹)	400 to	1200
_	Free speed	setting	Speed Level	Level	1 to 9
ive	1 100 opcou	HARD fastening	(min ⁻¹)	100 t	o 700
wdr		setting	Speed Level	Automatically set by torque setting	
Screwdriver	Power Cons	umption	(W)	44	
	Screw Size	Machine Screw	(mm)	3.0 to 6.0	
Electric		Tapping Screw	(mm)	2.5 t	o 5.0
Ele	Bit Type		(mm)	23 9	6.35
	Mass		(kg [lbs])	0.63 [1.39]	
	Standard Ac	cessories		Bit NK35 (No.2×7×7) Connection Cord 2 r Suspension Bail: 1 p	n (DLW9078): 1 pc.

	Model	DCC0241X-AZ	
Controller	Input Voltage	100 - 240 V AC, 50/60 Hz	
	Output Voltage	40 V DC	
	Input Signal Method	Photocoupler input (24 V DC drive (5 mA/1 input), NPN/PNP switchable)	
	Output Signal Method	Photocoupler output (30 V DC or less, 80 mA/1 output or less, NPN/PNP switchable)	
ပိ	Service Power Source	24 V DC (Maximum capacity 200 mA)	
	Serial Signal Method	RS-232C	
	ESD (Electrostatic Discharge) Protection	Adopted (IEC61340-5-1 compliant)	
	Mass (kg [lbs])	1.8 [3.97]	

Caution

- Speed and torque differs depending on the temperature. (Use within the range of + 10 to +40 $^{\circ}\text{C}$)
- *Do not retighten screws that are already tightened. The torque will become larger than the set torque.

About optional accessories (See page 9 "Optional Accessories")

*The power cord for the controller (DCC0241X-AZ) is sold separately.

Ask us for the required power cord when ordering.

- *For torque measurements, please use Nitto Kohki's Torque Checker and Soft Joint / Hard Joint (sold separately).

thirty screwdrivers can be consolidated into one.

5th unit 3.0 Nm 1000 min-1

30th unit 3.0 Nm 400 min-1





Two types of fastening mode available subject to the workpiece and fastening conditions. Coordinate the actual workpieces, screws and operating conditions and determine the fastening mode, torque range and rotation speed.

SOFT / HARD fastening Settings

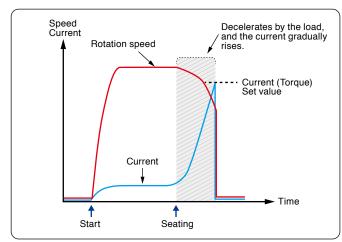
Instruction manual P68, P69

SOFT fastening setting

Suitable for workpieces with high fastening load such as tapping screws or fastening soft objects such as rubber.

Timing chart

The image of the control action, seating the screw at the set rotation speed.

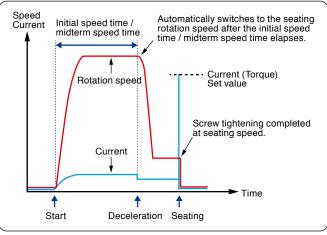


HARD fastening setting

Suitable for workpieces with small fastening load such as threaded holes or rigid bodies such as metal.

Timing chart

A control that seats the screw at the seating rotation speed according to the torque setting value, when the initial speed time / midterm speed time is elapsed.



^{*}When measuring the torque with Torque Checker, use Soft Joint (DLW4050) for SOFT fastening setting, use Hard Joint (DLW4040) for HARD fastening setting. (See page 9)

Torque range: Output Torque and Rotation Speed

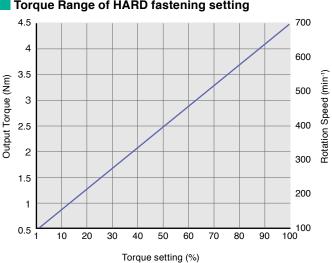
Instruction manual P11, P12

There are nine levels for rotation speed setting. (400 to 1200 min⁻¹) Corresponds to high torque fastening, even at SOFT fastening setting or slow rotation speed. (Corresponds to a maximum of 3 Nm at 400 min⁻¹)

■ Torque Range of SOFT fastening setting

Nine setting levels available Output Torque (Nm) 3 2 1.5 2 Lv1 Lv2 Lv3 Lv4 Lv5 Lv6 Lv7 Lv8 Lv9 (400 min⁻¹) (500 min⁻¹) (600 min⁻¹) (700 min⁻¹) (800 min⁻¹) (800 min⁻¹) (1000 min⁻¹) (1100 min⁻¹) (1200 min⁻¹) (1200 min⁻¹)

Torque Range of HARD fastening setting

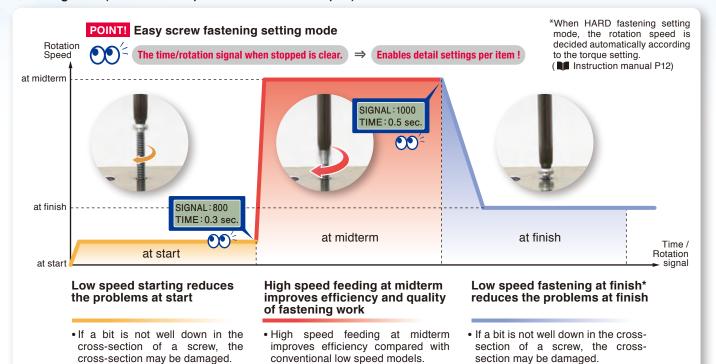


Rotation speed: Built-in automatic speed control function

Instruction manual P30 to P32

Built-in automatic three step variable speed control function. Enables compatibility of "quality of slow speed" and "efficiency of high speed". Low speed at start High speed feeding Low speed fastening

○ Timing chart (Below rotation speeds and times are examples)



· Low speed starting and low speed

fastening at finish improve quality of

screw fastening work compared with

conventional high speed models.

Screw fastening time measuring (Upper / Lower limit)

· If a screw does not fit in a thread,

and seated partially.

the screw may be cross-threaded

Instruction manual P32

· High speed fastening from start to

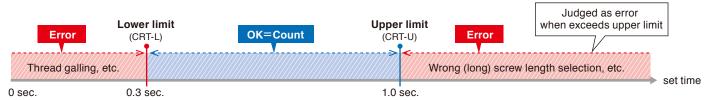
finish generates overshoot torque

(over-tightening by an inertial force)

and may cause breakage of a screw

neck part.

The upper / lower limit of screw fastening time (correct timer) can be set. It will be judged as "correct fastening" only when the measured time is between the upper limit and lower limit. Either limit can be switched off.



Two types of measuring methods

Instruction manual P41

There are two methods to measure the setting time of start and midterm.

\odot

TIME

Measure by time. You can decide the setting value intuitively.



MOTOR SIGNAL

Measure by the motor rotation signal. Even if you change the rotation speed, you do not need to set the measurement time or rotation time.

Rotation direction setting

Instruction manual P37

Specify the rotation direction of forward rotation. "RIGHT" for clockwise, "LEFT" for counterclockwise.



Channel setting

Instruction manual P4, P28, P70

The unit of fastening work performed continuously under the same conditions is called a "channel". Up to thirty channels can be registered in the memory.



Example of motion setting

Channel Motion setting	CH1	CH2	СНЗ	CH4		CH30
1: Screw fastening mode	SOFT	SOFT	HARD	SOFT		HARD
2: Number of screw fastening	2 pcs.	13 pcs.	5 pcs.	3 pcs.	• • • • • • • • • • • • • • • • • • • •	20 pcs.
3: Speed level at finish	Lv5	Lv9	AUTO	Lv1		AUTO
4: Torque	10%	80%	30%	45%	• • • • • • • • • • • • • • • • • • • •	20%
5: Speed level at start	Lv1	OFF	Lv9	Lv3		Lv1
6: Rotation time at start	0.1 sec.	_	0.3 sec.	0.8 sec.	• • • • • • • • • • • • • • • • • • • •	1.0 sec.
7: Speed level at midterm	Lv9	OFF	OFF	Lv8		Lv7
8: Rotation time at midterm	0.5 sec.	_	_	1.2 sec.	• • • • • • • • • • • • • • • • • • • •	0.5 sec.
9: Speed level at reverse rotation	Lv9	Lv9	Lv7	Lv5		Lv5
:	:	:	:	:		:
26: Rotation direction	RIGHT	RIGHT	RIGHT	LEFT		RIGHT

Channel pattern setting

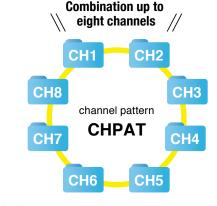
Instruction manual P4, P38, P70

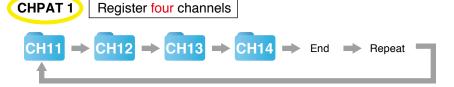
A series of operations combining each channel is called a "channel pattern". Up to eight channels can be registered per channel pattern.

Up to thirty channel patterns can be set.

When combining nine or more channels, use multiple channel patterns.

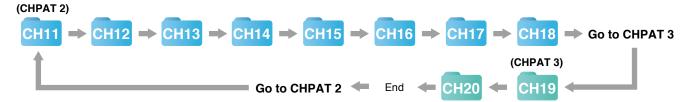












Setting lock function

Instruction manual

Entry of password to enter channel setting mode can be enabled/disabled. Prevents unintended setting change.



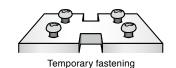
--COM SETTING--SETTING LOCK: ON

flashing

Auto reverse function

Instruction manual

The screwdriver automatically reverses after torqueup or reaching the preset time. Auto reverse mode can be used for temporarily fastening screws or verifying tapped holes.



Verifying tapped holes

Built-in LED function Instruction manual P19, P37

The LED at the tip of the electric screwdriver is always lit in the specified color. Color coding for each channel is possible.

Also, it lights in the specified color when OK(PASS) / NG(FAIL) / count up.





Controller

Two safety functions

1. Caution mode Instruction manual P43

A torque value that alerts the operator can be set. After the channel is switched, if the torque exceeds the preset value, a warning is displayed on the counter and the electric screwdriver will not start.





Flashes in yellow

2. Refastening prohibited time setting Instruction manual P36

To prevent additional fastening (second tightening, confirmation tightening, etc.), it can be set so that it does not restart after torque-up (for 0.0 to 9.9 seconds).

Adjust the set value according to the skill level of the operator and the interval between screw fastening operations.





Controller Flashes in red

External I/O signal

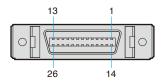
When connecting to an external device, it can be connected in two ways.

1. External I/O Cable

Instruction manual P47 to P52

Use External I/O Cable DLW9091. Compatible with both NPN/PNP.

It can be wired according to the externally connected equipment.



Connector: IEEE1284 half pitch connector (26-pin)

Terminal No.	Function	Details	
1	+24 V DC	Built-in service power supply (Capacity: Maximum 200 mA)	Service
2	0 V DC	Dulit-III Service power supply (Capacity: Maximum 200 IIIA)	supply
3	Input signal common terminal	Input signal common terminal (See page 49 of instruction manual)	Input
4	Output signal common terminal	Output signal common terminal (See page 50 of instruction manual)	Output
5	Switching signal A		
6	Switching signal B		
7	Switching signal C	Specify channel or channel pattern using a 5-bit input signal.	
8	Switching signal D		
9	Switching signal E		Input
10	Forward rotation start	Startup with external input signal.	
11	Reverse rotation start	The electric screwdriver operates while the input signal is ON.	
12	Workpiece	Input workpiece signal (workpiece detection signal output). Workpiece signal is ON while input signal is ON.	
13	External reset	Input external reset signal	1
14	N/A	No connection	_
15	Channel A		
16	Channel B		
17	Channel C	The channel being operated or being set is ON	
18	Channel D		
19	Channel E		
20	Forward rotation signal	Output signal is ON during forward rotation	
21	Reverse rotation signal	Output signal is ON during reverse rotation	Output
22	Operation OK	Output signal is ON when the screw fastening of the set count is complete and judged as operation OK (PASS).	
23	Count up	Count up Output signal ON for 0.3 seconds when screw fastening is normal (at torque-up).	
24	Operation NG	Output signal ON when workpiece signal is OFF during operation and judged as operation NG (FAIL).	
25	Screw fastening NG	Output signal ON for 0.3 seconds when screw fastening is NG (FAIL).	
26	N/A	No connection	

2. RS-232C

Instruction manual P55 to P58

Use Communication Cable (Straight-through) DLW9092 to connect with PCs or sequencers (PLC).

5	5	1
	0000	
	9 6	3

Connector pin layout (D-SUB 9-pin (female))

♦ Specifications (RS-232C)

Transmission method	Asynchronous (asynchronous communication)
Communication line	Full duplex
Transmission speed	38400 bps
Number of data	8
Parity	None
Stop bit	1
Handshake	None
Delimiter	Receive: CR+LF (¥r¥n)
(communication separator)	Send: CR+LF (¥r¥n)

Pin No.	Signal name	I/O
2	TxD	OUT (This tool⇒PC)
3	RxD	IN (PC⇒This tool)
5	GND	GND

*Other pins are not used

♦ Send / receive commands

Operation	Send command	Response from controller	
Forward rotation drive	FWD¥r¥n	FWD¥r¥n	
Reverse rotation drive	RVS¥r¥n	RVS¥r¥n	
Drive stop	STP¥r¥n	STP¥r¥n	
Switching channel / channel pattern *1	MOV:p¥r¥n (p=1 to 30)	At channel switching CH :p¥r¥n At channel pattern switching CHP:p¥r¥n	
Screw count reset	CRT¥r¥n	CRT¥r¥n	
Workpiece reset	WRT¥r¥n	WRT¥r¥n	
Workpiece signal ON	WIN¥r¥n	WIN¥r¥n	
Workpiece signal OFF	WOT¥r¥n	WOT¥r¥n	
Resend request *2 RSD:p¥r¥n (p=1 to 10)		Command sent nth time before, specified by the parameter value	

^{*1} The switching target differs depending on the setting of the common setting "Channel change type" (CH CHANGE).

[Example] Send command "RSD:3\forall r\forall n" \to Returns the command sent by the controller three times before.

Since control is performed even when communication between the controller and PC or sequencer fails, use this function when you wish to maintain the reliability of transmission and reception. This command transmission is not included in the ten commands that are stored.

Notification command

In addition to RS-232C signals, commands are sent from the controller to the PC or sequencer(PLC) when processing is performed manually or by contact signals.

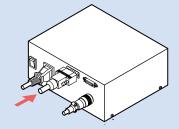
Operation	Notification from controller
At forward rotation drive start	FWD¥r¥n
At reverse rotation drive start	RVS¥r¥n
At drive stop completion	STP¥r¥n
Operation OK (PASS) notification	OK ¥r¥n
Workpiece signal ON	WIN¥r¥n
Workpiece signal OFF	WOT¥r¥n
Count up (screw fastening completes normally) notification	CUP:p¥r¥n
p = Measured fastening time or signal is output	(p=1 to 60000)
Operation NG (workpiece out while fastening count remaining) notification	WNG¥r¥n
Screw fastening NG (FAIL) notification pt=Screw fastening NG (FAIL) No.	ENG:n1:n2\r\r
p1=3crew rastering NG (FAL) No. p2=Measured fastening time or signal is output	FNG:p1:p2¥r¥n
	CH :p¥r¥n
At channel switching	(p=1 to 30)
At channel nattern ewitching	CHP:p¥r¥n
At channel pattern switching	(p=1 to 30)
When a non-supported command or parameter is input	CER¥r¥n

1. External I/O Cable DLW9091

Insert the separately sold External I/O Cable DLW9091 to the external signal connector to connect between the terminal and wiring.







Insert the separately sold Communication Cable (Straight-through) DLW9092 to the RS-232C connector to connect to a PC or sequencer (PLC).

When the channel pattern is switched, the channel is also switched, so the responses are sent continuously.

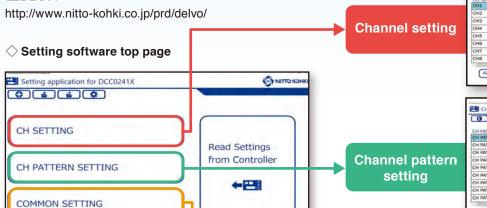
^{*2} Up to the latest ten commands sent from the controller to the PC or sequencer are stored. When signals could not be received correctly due to noise or some other reason, the command of nth time before, specified by the parameter will be sent from the PC or sequencer.

Easy setting with dedicated software

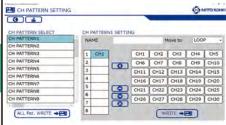
Channels and Channel patterns can be easily set with dedicated software. Download free from our website.











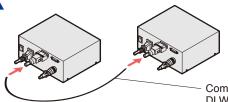


Setting data transmission function between controllers

Instruction manual P45

The channel and channel pattern settings can be transmitted to another controller.

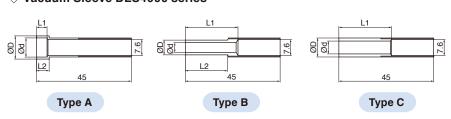
This is very convenient when the same work is divided into multiple processes.



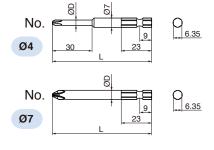
Communication Cable (Crossover) DLW9093

Vacuum Sleeves and applicable Bits

♦ Vacuum Sleeve DLS4000 series



Model	Ød	ØD	L1	L2	Length	Applicable Bit *2	Shape (Type)	Part No.
DLS4220	9.1	11	5	6		No.2x7x75	Α	TD08001
DLS4221	10.6	12.5	5.5	7		No.2x7x75	Α	TD08002
DLS4222 *1	8	11	5.3	22		_	Α	TD07850
DLS4223 *1	8.2	10	5	6		No.2x7x75	Α	TD07851
DLS4224 *1	6.8	9	25	_	1 45	_	С	TD07852
DLS4225	4.6	7	25	20	45	No.1x4x75	В	TD09344
DLS4226	5.1	7	25	20		No.1x4x75	В	TD09617
DLS4227	5.6	7	25	20]	No.2x4x75	В	TD09345
DLS4228	6.1	9	25	_		No.2x4x75	С	TD09618
DLS4229	6.4	9	25	_		No.1x4x75	С	TD09619
DLS4230	7.1	9	25	_	1	No.2x4x75	С	TD09620



No.	ØD	L	Part No.
	4	75	TD20306
1	7	50	TD20308
	7	75	TD20309
	4	50	TD20316
2	4	75	TD20317
2	7	50	TD20319
	7	75	TD20320
3	7	50	TD20327
<u> </u>	7	75	TD20328

^{*} See delvo general catalog for other bit types.

Optional Accessories

Grounded 3-Prong Power Cord 2 m

DLW9220 North America



DLW9240 Europe



DLW9250 UK



Diamond Shape Flange Coupling DLW9017



For mounting on automated screw fastening machines

Flange Coupling DLW9019



For mounting on automated screw fastening machines

Screw Vacuum Pump DLP2540 (115 V AC), DLP2570 (230 V AC)



Connect the tube to the vacuum pickup port. The vacuum will pick up the screw.

Vacuum Pickup DLP7401-K



For screw vacuum pickup

Vacuum Sleeve DLS4000 series



Select according to the screw shape

Torque Checker DLT1673A



For torque control of screwdrivers

Soft Joint DLW4050





The bit for measuring is included. (NK35BN 13×19×10×75)

For SOFT fastening torque measurement

Hard Joint DLW4040







The bit for measuring is not included. (NK35BN 13×19×10×75)

For HARD fastening torque measurement

External I/O Cable 3 m DLW9091



Connect when using external signals

Communication Cable 3 m (Straight-through)
DLW9092



Connect to PCs and PLCs (sequencers) when using external signals

Communication Cable 3 m (Crossover) DLW9093



Connect controllers to transmit settings

Extension Cord 3 m DLW9310



Extends cord length between controller and screwdriver

Connection Cord 2 m DLW9078



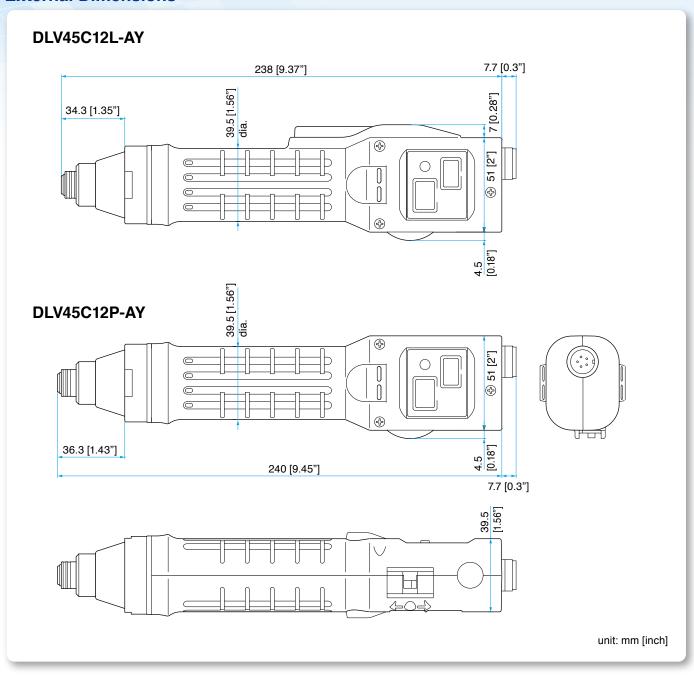
Connects controller and screwdriver

Pistol Grip DLW2300ESD

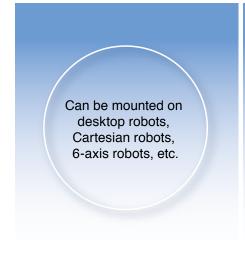


For operator fatigue reduction, suitable for horizontal fastening

External Dimensions



Example of installation on automated machines

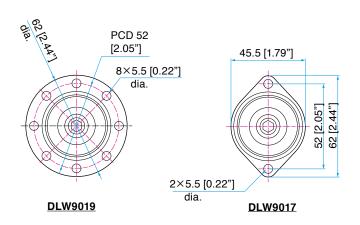


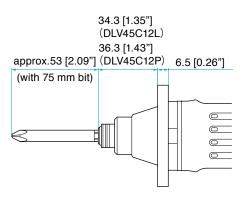




External Dimensions

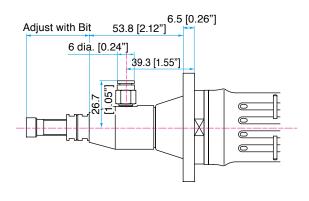
When Flange Coupling DLW9019/DLW9017 is mounted

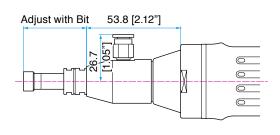




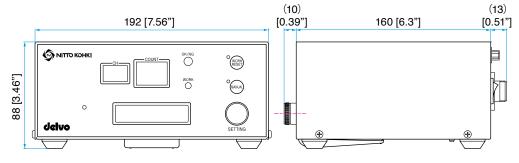
When Flange Coupling and Vacuum Pickup DLP7401-K is mounted

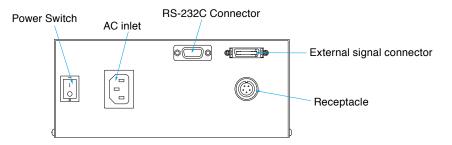
When Vacuum Pickup DLP7401-K is mounted





Controller DCC0241X-AZ





unit: mm [inch]

